

OMRON

MICROSCAN

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SUPPORTING YOUR SUCCESS



VÉHICULES INTELLIGENTS AUTONOMES

Robots mobiles LD

Modernisez votre flux de travail

Nos robots mobiles autonomes sont des véhicules intelligents autonomes (VIA ou AIV) conçus pour augmenter considérablement la productivité dans les opérations de fabrication et de logistique. Non seulement nos robots mobiles rendent vos employés plus efficaces en leur permettant de se concentrer sur les tâches qui exigent des compétences humaines complexes, mais ils augmentent le débit, réduisent les temps d'arrêt machine, éliminent les erreurs et améliorent la traçabilité des matériaux.

Flexible

Conceptions de charge personnalisables

- Intégration facile avec les convoyeurs existants
- Compatible avec les bras robotisés
- Chariots et casiers de transports
- Puissance, entrées-sorties, Wi-Fi



Sécurité

Pleine conformité aux normes de sécurité

- Fonctionne en collaboration avec les employés
- Capable d'éviter les obstacles statiques et mobiles
- Ajout facile d'équipement d'arrêt d'urgence



Facile à déployer

Circulation avec les caractéristiques naturelles du site

- Réduit les coûts : pas de modifications des installations
- Aucune préprogrammation du trajet
- Automappage grâce au PC embarqué
- Temps d'installation réduit

Efficace

Optimisez vos opérations

- Prend toujours le chemin le plus court possible
- Planification automatique des itinéraires de remplacement
- Ajoutez facilement des points de ramassage et de livraison

Évolutif

Flottes de 100 véhicules maximum

- Gestion et répartition du travail
- Gestion centralisée de la configuration et des cartes
- Facilite la circulation sur le site
- Point de communication centralisé

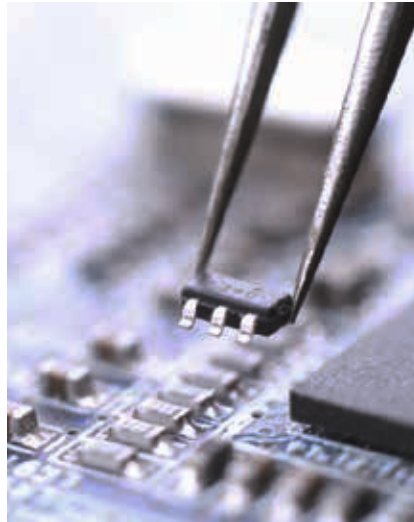
Conception robuste : productif 24 h/24 et 7 j/7

- Charge intelligente
- Capable de fonctionner dans un environnement très dynamique
- Déjà adopté dans tous les pays du monde
- >17 ans d'expérience continue

Des milliers de possibilités de gains de productivité

Aujourd'hui, nous avons le plus grand parc de véhicules intelligents autonomes dans la fabrication.

Nos robots mobiles peuvent être déployés dans des milliers d'applications dans de nombreux secteurs industriels.



Automobile

Montage des pneus

Transportez les pneus verts du lieu d'entreposage intermédiaire à la presse de vulcanisation.

Électronique automobile

Transportez les sous-ensembles de la mise en lots au réapprovisionnement latéral.

Accessoires automobiles

Transportez des casiers vers et depuis les stations de moulage par injection.

Numérique

Fabrication de wafers de semi-conducteurs

Transport WIP intrajournalier entre différents entrepôts d'outils pour traitement ou de réticules pour photolithographie.

Emballage et test de semi-conducteurs

Transportez des plateaux de circuits IC par chariot.

Fabrication d'appareils mobiles

Transportez des casiers de circuits imprimés dans une usine d'assemblage de combiné.

Centre de données

Surveillance de l'environnement (température, humidité, etc.) et dépannage.

Logistique

Entrepôt

Traitement de commandes e-commerce.

Centre de distribution pour expédition

Transportez des casiers des étagères aux quais de chargement.



Biens de consommation

Fabrication de bijoux

Transportez des moules de bijoux finis vers les stations de moulage.

Accessoires du concepteur

« Convoyeur virtuel » pour transporter des caisses de lunettes de soleil à partir de stations de tri manuel ASRS.



Alimentation, boissons et secteur hôtelier

Établissement de restauration

Transportez des casiers de nourriture préparée vers la réserve.

Hôtellerie

Livraison de linge et service de chambre.



Médical

Stérilisation

Transportez les instruments chirurgicaux vers la salle de stérilisation.

Laboratoire d'analyse du sang

Sécurisez le transport de l'échantillon.

Technologie avancée et intégrée

Cartographie et navigation

Navigation fiable avec Acuity (breveté)

Le système Acuity fournit une méthode de « localisation » supplémentaire au laser embarqué pour permettre au robot de fonctionner dans des environnements en évolution constante. Il assimile l'éclairage au plafond pour identifier des repères lumineux qu'il utilisera avec la carte des lieux. Il permet également aux robots de se déplacer facilement entre les espaces ouverts des grands entrepôts.



Sécurité

Nos robots mobiles sont entièrement conformes aux normes de sécurité¹. Ils utilisent un laser embarqué et d'autres capteurs pour détecter des obstacles sur leur chemin et, en fonction de la vitesse de déplacement, déclenchent un arrêt d'urgence pour éviter la collision du véhicule.

Capteurs :

- Laser principal avec niveau de sécurité certifié
- Laser inférieur
- Lasers latéraux (brevetés)
- Pare-chocs avant
- Sonar arrière
- Laser arrière

¹ Norme de sécurité : ISO 12100, ISO 14121-2, ISO 13849-1, IEC 61010 (batterie uniquement), IEC 60950 (Batterie uniquement), EN 1525, ANSI B56.5 Partie 3, JIS D 6802, IEC 60204

Pourquoi nos robots mobiles sont-ils les véhicules intelligents autonomes les plus sophistiqués ?



Gestion de la flotte

Enterprise Manager

Enterprise Manager est un appareil réseau qui assure la coordination de robots mobiles tout en assurant la traçabilité, l'affectation de tâches et le contrôle de la circulation sur l'ensemble de la flotte.

Répartition des demandes de transport (tâches) :

Répartit les tâches entre robots mobiles en sélectionnant le meilleur véhicule pour effectuer le travail.

Contrôle de la circulation :

Optimise la circulation des véhicules.

Communications :

Point de contact unique pour l'intégration avec les systèmes d'usine (MES, WMS, ERP, etc.).

MobilePlanner :

Interface utilisateur logicielle basée sur PC pour la gestion du robot ou de la flotte.



Laissez-nous vous aider à mobiliser vos opérations

Réseau de collaboration mondiale

Prise en charge de l'expertise en robotique et de l'automatisation de machines par une équipe mondiale unique.



40 pays

150 lieux

3 000 ingénieurs en applications

Planification.
Mise en œuvre.
Prise en charge.

Nous sommes prêts à vous aider à chaque étape du chemin, n'importe où dans le monde.

Contactez-nous. Notre étude de faisabilité par des experts peut vous aider à déterminer si les véhicules autonomes mobiles sont adaptés à votre application.



Test avec de vrais produits



Simulations

Mobile Robots LD Series



Autonomous Intelligent Vehicles (AIVs), self-mapping, self-navigation.

- Natural-feature navigation
Automatically plans routes to prevent collisions
- Fleet management
Supervises and coordinates the entire fleet of up to 100 vehicles
- Easy deployment
Short installation time: no facilities modifications





Ordering Information

Mobile Robots-LD Platform





Appearance	Product Type	Product Name	Maximum Load	Maximum Speed	Configuration & Attachment	Model	
	OEM	LD-60	60 kg	1.8 m/s	Standard	-	37031-00000
					Docking Station kit	Docking Station : 12477-000 Battery Power Cable (0.45 m) : 12676-000	37031-00002
					Starter kit	Docking Station : 12477-000 Battery Power Cable (0.45 m) : 12676-000L MobilePlanner Software Licence : 13495-200 Joystick : 13558-000 Top Plate : 12944-000	37031-10004
		LD-90	90 kg	1.35 m/s	Standard	-	37041-00000
					Docking Station kit	Docking Station : 12477-000 Battery Power Cable (0.45 m) : 12676-000	37041-00002
					Starter kit	Docking Station : 12477-000 Battery Power Cable (0.45 m) : 12676-000L MobilePlanner Software Licence : 13495-200 Joystick : 13558-000 Top Plate : 12944-000	37041-10004
	Cart Transporter	LD-105CT	105 kg	1.35 m/s	Standard	Touchscreen :13605-000 Side Laser :13456-000	37141-00010
					Docking Station kit	Touchscreen :13605-000 Side Laser :13456-000 Docking Station :12477-050 Battery Power Cable (0.45 m) :12676-000	37141-00012
					Starter kit	Touchscreen :13605-000 Side Laser :13456-000 Docking Station :12477-050 Battery Power Cable (0.45 m) :12676-000L MobilePlanner Software Licence :13495-200 Acuity Localization :13700-000 Joystick :13558-000 Cart :75020-000	37141-01014
		LD-130CT	130 kg	0.9 m/s	Standard	Touchscreen :13605-000 Side Laser :13456-000	37161-00010
					Docking Station kit	Touchscreen :13605-000 Side Laser :13456-000 Docking Station :12477-050 Battery Power Cable (0.45 m) :12676-000	37161-00012
					Starter kit	Touchscreen :13605-000 Side Laser :13456-000 Docking Station :12477-050 Battery Power Cable (0.45 m) :12676-000L MobilePlanner Software Licence :13495-200 Acuity Localization :13700-000 Joystick :13558-000 Cart :75020-000	37161-01014

Software/Controller



Appearance	Product Name	Configuration & Attachment	Model
	MobilePlanner	Installer (USB) * License dongle	13495-200
	Enterprise Manager 1100	License dongle	11167-100



* .The latest version of MobilePlanner can be downloaded from Omron Adept Technologies Inc. website.
<http://www.adept.com/Robots-Mobile>

Options

Appearance	Product Name	Specification	Configuration & Attachment	Model
	High Accuracy Positioning System	Single sensor	Sensor × 1 , Mounting bracket × 1 , Power connector × 1 , RS-232 connector × 1 , 25 mm wide magnetic tape South top side. 50 m roll	13660-100
		Double sensor	Sensor × 2 , Mounting bracket × 2 , Power connector × 1 , RS-232 connector × 2 , 25 mm wide magnetic tape South top side. 50 m roll	13660-000
		Magnetic tape	25 mm wide magnetic tape South top side. 50 m roll	14925-000
	Acuity Localization	-	Camera, Mounting Kit, Cables, Leveling kit	13700-000
	Touchscreen	-	Touchscreen with bracket, Power supply with bracket, Power Cable, from core to power supply (33 cm in length), Power Cable, from power supply to touchscreen (183 cm in length), Ethernet Cable, between touchscreen and core (153 cm in length), Gasket, between touchscreen and AIV mounting surface, Software package, including touchscreen support	13605-000
-	Side Laser	Bundle	Laser × 2, Cable × 1 (Y Cable for 2 Laser)	13456-000
		Kit	Laser × 2, Cable × 1 (Y Cable for 2 Laser), Mounting kit × 2, Metal Cover × 2	13456-100
	Call/Door Box	WiFi Wired	Call/Door Box, Cable	13029-802

Accessories

Appearance	Product Name	Specification	Configuration & Attachment	Model
	Battery	-	-	18578-000
	Docking Station	-	Docking Station, AC Power Cable	12477-000
		Extended Wall mount	Docking Station, AC Power Cable, Extended Wall mount (for Cart Transporter)	12477-050

Appearance	Product Name	Specification	Configuration & Attachment	Model
	Joystick	Cable length: 0.6 to 3 m	-	13558-000
-	Breakout Cable	-	DB44HD Breakout Cable (D-SUB44 pin Cable for Digital I/O interface)	14165-000
-	Top Plate	Top cover for OEM type	-	12944-000
	Cart	-	-	75020-000
-	Battery Power Cable	Cable length: 0.45 m	-	12676-000L

Specifications

Mobile Robots-LD Platform General Specifications

Item	OEM		Cart Transporter		Note
	37031-@@@@@	37041-@@@@@	37141-@@@@@	37161-@@@@@	
Materials	KYDEX				
Dimension (L × W × H)	699 × 500 × 383 mm		894 × 1074 × 1394 mm *		*. Height includes WiFi antenna.
Weight (with Battery)	62 kg		81 kg (Vehicle)/23 kg (Cart)		
Environment	Ambient temperature	5 to 40 °C			
	Ambient humidity	5 to 95 % (non-condensing)			
	Operating Environment	Indoor usage only, No excessive dust, no corrosive gas			Direct sunlight may cause safety laser false positive
	IP rating	IP20			
Cleanroom rating	Fed Class 100, ISO Class5		None		

AIV (Autonomous Intelligent Vehicle) Specifications

Item	OEM		Cart Transporter		Note	
	37031-@@@@@	37041-@@@@@	37141-@@@@@	37161-@@@@@		
Floor Conditions	Floor Requirements	Level surface or concrete (no water, no oil, no dirt)				
	Minimum floor flatness	F _F 25 (* ACI 117 standard)				*. ACI 117 is the American Concrete Institute's standard for concrete floors. FF is flatness, FL is the level. Higher FF numbers represent flatter floors. FF25 is a fairly lenient specification.
	Traversable step	15 mm max. *1	10 mm max. *1	5 mm max. *2	5 mm max. *2	*1. A speed of 250-300 mm/s and 250 mm/s, for the LD-60 and LD-90, is required for these steps. Faster or frequent driving over such steps or gaps will shorten the lifespan of the drivetrain components. Lower speeds may not traverse the step. Steps should have smooth, rounded profiles.
	Traversable gap	15 mm max.	15 mm max.	5 mm max. *2	5 mm max. *2	*2. The Cart transporter with a cart is capable of driving over a gap or step of 5mm at a speed of 250 mm/s, but this should not be regarded as normal use. Regular driving over such gaps or steps will shorten the lifespan of the drivetrain components.
	Climb grade	Below 1: 12 (60 kg max.) Flat floor only (over 60 kg)		Flat floor only		
Navigation	Routing	Autonomous routing by localizing with Safety Scanning Laser based on environment mapping.				
	Environmental map making method	Scan by walking the Mobile Robot through the environment, and upload the Scan data in the MobilePlanner.				
Payload	Maximum Weight	60 kg	90 kg	105 kg *	130 kg *	*. Excluding cart weight

Item		OEM		Cart Transporter		Note
		37031-@@@@@	37041-@@@@@	37141-@@@@@	37161-@@@@@	
Mobility	Maximum speed	1800 mm/s	1350 mm/s	1350 mm/s	900 mm/s	
	Maximum rotation speed	180°/s	180°/s	100°/s		
	Stop position accuracy	± 100 mm: Position *, ± 2°:Rotation				*. ±10 mm: Position, ±0.5°: Rotation with option, (High Accuracy Positioning System)
Drive wheel	Materials	Non-marking Nylon foam-filled rubber, non-conductive				
	Size	200 dia. × 50mm nominal, 2 wheels				
Passive caster	Materials	Conductive thermoplastic rubber on Polyolefin				
	Size	75 dia. × 41 mm nominal, 4 casters				
Power	Battery	22-30 VDC				
	Capacity	72 Ah Battery cell nominal capacity				
	Run time	15 hours (continuous) approx.				With no payload condition
	Recharge Time	4 hours (5:1 ratio) approx.				
	Battery Life cycles	2000 recharge cycles (Battery cell nominal)				
	Charging method	Automatic / Manual				
	Auxiliary Power	5 VDC±5%, 1 A Switched Aux power 12 VDC±5%, 1 A Switched Aux power 20 VDC±5%, 1 A Switched Aux power 22-30 VDC, 4 A Switched × 2 22-30 VDC, 10 A Switched * 22-30 VDC, 10 A Safe, Switched *				5, 12, 20, and 22-30 VDC power can be provided to external devices. *. 10 A Switched and 10 A Safe, Switched share the 10 A of current.
Standard	Safety Standard	EN1525 / JIS D6802 / ANSI B56.5				
	Wireless	IEEE 802.11 a/b/g				
Safety Features	Safety Scanning Laser	1 at front Class 1 PLd Safety per ISO13849-1 Maximum range: 15 m Field of view: 240°				
	Emergency Stop	1 at Operator panel		1 at HMI post touchscreen, 1 at Operator panel		
	Rear sonar	2 at rear, 2 m range				Each pairs is one emitter and one receiver, working together
	Front Bumper	1 at front of platform, 2pairs of sensors				
	Low Front Laser	1 at front of platform Class 1 Maximum range: 4 m Field of view: 270°				
	Side Laser	Option *		2 on horizontal tubes of HMI post Class 1 Maximum range: 4 m Field of view: 270°		*. 2 on sides of payload structure, user-mounted
	Flash light	Light Disc in each side		Light Disc in each side, Beacon on HMI post		
	Speaker	3.5", 80 W max.				
Operator Interface	Screen / Touch panel	3.5 in. TFT 320 × 240 pixels, 256 K color screen		7.0 in. TFT LCD touch panel , 18/24 bit RGB		
	Button	ON Button: Green, OFF Button: Red, Brake-release button: Orange, Keypress (Disabled OFF Button)		ON Button: Green, OFF Button: Red, Brake-release button: Orange, Keypress (Disabled OFF Button), Latch Button, Unlatch Button		
User I/F	Wireless	IEEE 802.11 a/b/g				
	Ethernet port	1 × User LAN , 1 × Maintenance LAN, Auto-MDIX				
	Serial	RS-232 × 2, CAN Bus B × 1				
	Digital I/O	16 inputs, 16 outputs				
	Analog I/O	8 inputs (0 to 30 V), 4 outputs (0-20 V)				
Cart Latching	Audio	Digital Audio Out, Audio In / Audio Out				
	Latching method	Not available		Automatic		

MobilePlanner

Model	13495-200
Operating system	Windows 7 (32-bit/64 bit version) / Windows 8 (32-bit/64-bit version) / Windows 10 (32-bit/64-bit version)
CPU	1.5 GHz dual-core CPU recommended
Main memory	1.5 GB min. (4 GB min. recommended)
Hard disk	At least 200 MB of available space
Video memory	256 MB min.
Display	XGA 1024 × 768, 16 million colors
Communications ports	USB port (for license key)
Supported languages	Japanese, English

Enterprise Manager 1100

Model	11167-100
Dimensions- W × D × H	426.0 × 438.4 × 42.4 mm
Weight	6.8 kg
Mounting method	1U rack mount in a standard 19-inch equipment rack
Power Supply	100-240 VAC *
Power Consumption	200W max.
Operating Temperature	10 to 35 °C
Storage Temperature	-25 to 60 °C
Operating Humidity	8 to 90%, non-condensing
Storage Humidity	5 to 95%, non-condensing
Chassis protection class	IP20
CPU	Intel® Xeon® CPU
Main Memory	4 GB DDR3
Storage	32 GB SSD
Communication port	10/100/1000 Ethernet × 4, USB × 4, VGA

*. typical 100 W

High Accuracy Positioning System

Model	13660-@00	
Sensor	Depth	30 mm
	Width	160 mm
	Rating	IP64
	Environment	-40 to 85 °C
	LEDs	Power, Tape present, Left marker, Right marker
Magnetic Tape	Width	25 mm
	Orientation	South up
Markers (Magnetic Tape)	Width	25 mm
	Length	300 mm min. for 500 mm/s drive speed
	Orientation	North up
Connections	Separation from tape	15 - 30 mm
	Front sensor	RS232-1 (/dev/ttyUSB9) on the core
	Rear sensor	RS232-2 (/dev/ttyUSB10) on the core
	Power, both sensors	Aux Power, using the included splitter cable

Acuity Localization

Model	13700-@00
Field of View	140°
Power Input	12 VDC (±10%) supplied from platform, through power connector
Power Consumption	3.3 W maximum

Touchscreen

Model	13605-000
Touch Panel	PCAP touch sensor, 5 simultaneous touches, black bordered cover lens
TFT Display	TFT LCD panel, 18/24 bit RGB parallel interface. 7.0 in. WVGA - Wide Viewing Angles, 5-Touch
Backlight	Constant current LED supply
Power Input	5 VDC supplied through power connector
Power Consumption	6.5 W maximum

Call/Door Box

Model	13029-802
Dimensions- W × D × H	141.4 × 74.7 × 30 mm
Weight	190 g
Mounting method	Mount to the provided wall frame with four screws
Power Supply	12 VDC
Power Consumption	0.5 A, 6 W typical
WiFi	IEEE 802.11 a/b/g/n
Communication port	Ethernet
I/O	Input × 2, Output × 2 (30 VDC, 2 A max)

Battery

Model	18578-000
Run-time (no payload)	15 hours (continuous) approx.
Weight	19 kg
Voltage	22-30 VDC
Capacity	72 Ah (Battery cell nominal)
Recharge time	4 hours, approx.
Life time	2000 times 80% DOD (Battery cell nominal), 7 years, approx., 16 hrs/day, 5 days/wk 4 years, approx., 19/7 (full-time)

Docking Station

Model	12477-0@0
Current	8 A *1
Contacts	2
Power	100 to 240 VAC, 50 to 60 Hz
Power consumption	800 W
Humidity	5 to 95 % non-condensing
Temperature	5 to 40 °C
Dimensions- W × D × H	349 × 369 × 315 mm (495 × 495.5 × 317 mm) *2
Weight	8.2 kg
Mounting	Wall bracket, directly to floor, or on floor with floor plate
Indicators	Power on - blue Charging - yellow
Connector	For out-of-platform battery charging

*1. Thermal fuse in AC power switch (10 A Time-lag fuse at switch for legacy dock)

*2. () for with Floor plate

Joystick

Model	13558-000
Weight	550 g
IP rating	IP56

Cart

Model	75020-000
Dimension (L × W × H)	592 × 846 × 480 mm
Weight	23 kg
Rating	ESP rated
Passive Casters	2 front, 2 rear, spring-loaded
Caster diameter	100 mm nominal
Caster Brakes	at 2 rear casters

Components and Functions

OEM

Operator Panel

Power ON/OFF, Emergency Stop, Brake Button with 3.5 inch color monitor

WiFi antenna
IEEE 802.11 a/b/g

Top Plate (Option)
Upper plate come with Starter Kit.
It is not necessary for building customer payload.

Rear Sonar

Obstacle sensor to detect rear side based on Sonar.

Safety Scanning Laser
Safety rated Laser using for SLAM (Simultaneous localization and mapping).
It is also used for safety functionality.



Light Discs

Status indicator. Located both side

Front Bumper
Stop when it hits obstacle

Low Front Laser
Obstacle sensor to detect low profile object in the forward direction.

Cart Transporter

Operator Panel

- 7" Color touchscreen. (Status, Goal input)
- WiFi antenna x2
- Emergency Stop
- Power ON/OFF
- Brake Button
- Latch/Unlatch buttons for Cart
- Beacon
- Acuity Localization (Option)



Rear-facing Laser
Obstacle laser scanner to detect rear side.

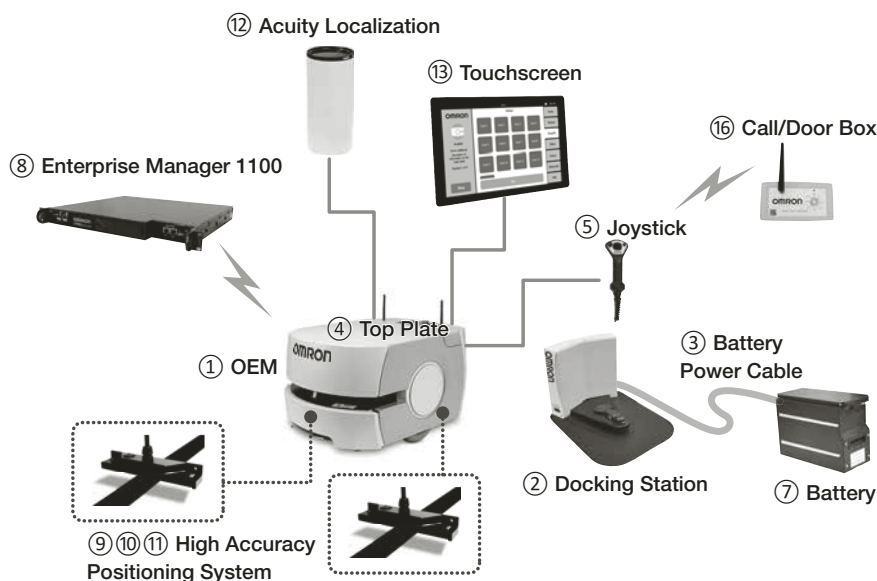
Side Laser
Obstacle laser scanner to detect vertically

Cart
Automatically latch/unlatched cart with manual break. Latching/Unlatching can be controlled by Software.

OEM
OEM with Cart Latching plate

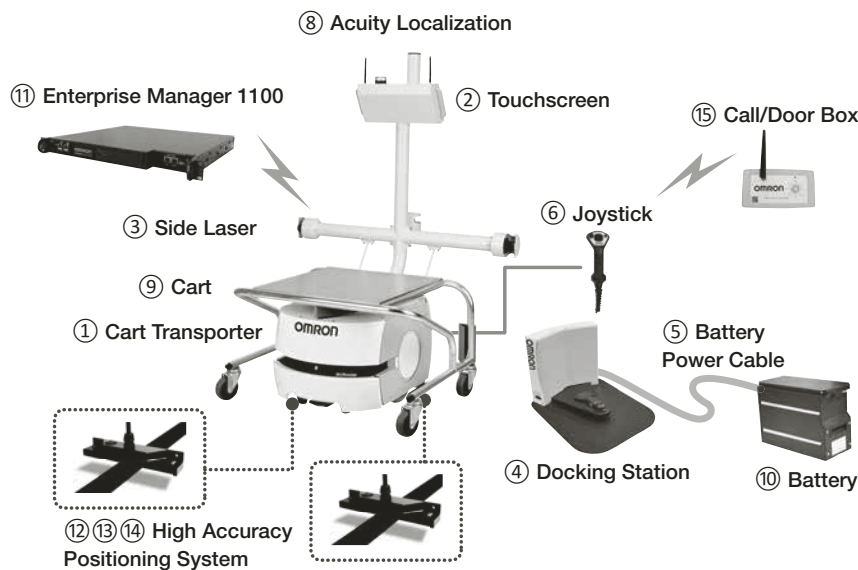
System Configuration

OEM



	Product Name	Model	Description	Docking Station kit/Starter kit
①	OEM	370@1-00000	A Mobile Robot OEM. The Battery is not included.	Included in Docking Station kit and Starter kit
②	Docking Station	12477-000	A docking station to charge the Battery installed in the Mobile Robot.	Included in Docking Station kit
③	Battery Power Cable	12676-000L	A cable to connect a Battery and Docking Station to charge the Battery outside of the Mobile Robot.	
④	Top Plate	12944-000	A upper plate of the Mobile Robot OEM. It is not necessary for building customer payload.	Included in Starter kit
⑤	Joystick	13558-000	Used for manually controlling the Mobile Robot.	
⑥	MobilePlanner	13495-200	PC software to configure, drive and observe the Mobile Robot, including a USB license dongle.	
⑦	Battery	18578-000	A Battery that is installed in the Mobile Robot.	-
⑧	Enterprise Manager 1100	11167-100	A system that manages a fleet of Mobile Robots, including a network appliance, software, and a USB license dongle.	-
⑨	High Accuracy Positioning System (Single sensor)	13660-100	A sensor and magnetic tape to achieve accurate alignment when the Mobile Robot follows driving forward. The sensor is attached to the Mobile Robot.	-
⑩	High Accuracy Positioning System (Double sensor)	13660-000	Two sensors and magnetic tape to achieve accurate alignment when the Mobile Robot follows driving both forward and backward. The sensors are attached to the Mobile Robot.	-
⑪	Magnetic tape	14925-000	Magnetic tape for the High Accuracy Positioning System. The tape is applied to signal the Mobile Robot where to stop.	-
⑫	Acuity Localization	13700-000	Used where process layout or obstacle location changes often. Installed on a payload structure attached to the Mobile Robot.	-
⑬	Touchscreen	13605-000	Allows operators to check the status of the Mobile Robot, enter goals, and pause the Mobile Robot. Installed on a payload structure attached to the Mobile Robot.	-
⑭	Side Laser Bundle	13456-000	Used to detect obstacles that are at heights the safety scanning laser of the Mobile Robot cannot detect. Installed on a payload structure attached to the Mobile Robot.	-
⑮	Side Laser Kit	13456-100	Includes the above mentioned Side Laser, mounting kit, and metal covers to protect from lasers.	-
⑯	Call/Door Box	13029-802	Used to issue a request for a Mobile Robot to go to the goal or to open a closed door. Installed at the goal or door to open.	-
⑰	Breakout Cable	14165-000	A D-SUB44 pin cable for digital I/O interface of the Mobile Robot.	-

Cart Transporter



	Product Name	Model	Description	Docking Station kit/Starter kit
①	Cart Transporter	371@1-00000	A Mobile Robot Cart Transporter. The Battery is not included.	Included in Docking Station kit and Starter kit
②	Touchscreen	13605-000	Allows operators to check the status of the Mobile Robot, enter goals, and pause the Mobile Robot. Installed on a payload structure attached to the Mobile Robot.	
③	Side Laser	13456-000	Used to detect obstacles that are at heights the safety scanning laser of the Mobile Robot cannot detect. Installed on a payload structure attached to the Mobile Robot.	
④	Docking Station	12477-000	A docking station to charge the Battery installed in the Mobile Robot.	
⑤	Battery Power Cable	12676-000L	A cable to connect a Battery and Docking Station to charge the Battery outside of the Mobile Robot.	Included in Docking Station kit
⑥	Joystick	13558-000	Used for manually controlling the Mobile Robot.	
⑦	MobilePlanner	13495-200	PC software to configure, drive and observe the Mobile Robot, including a USB license dongle.	Included in Starter kit
⑧	Acuity Localization	13700-000	Used where process layout or obstacle location changes often. Installed on a payload structure attached to the Mobile Robot.	
⑨	Cart	75020-000	A cart designed for Mobile Robot Cart Transporter.	
⑩	Battery	18578-000	A Battery that is installed in the Mobile Robot.	-
⑪	Enterprise Manager 1100	11167-100	A system that manages a fleet of Mobile Robots, including a network appliance, software, and a USB license dongle.	-
⑫	High Accuracy Positioning System (Single sensor)	13660-100	A sensor and magnetic tape to achieve accurate alignment when the Mobile Robot follows driving forward. The sensors are attached to the Mobile Robot.	-
⑬	High Accuracy Positioning System (Double sensor)	13660-000	Two sensors and magnetic tape to achieve accurate alignment when the Mobile Robot follows driving both forward and backward. The sensors are attached to the Mobile Robot.	-
⑭	Magnetic tape	14925-000	Magnetic tape for the High Accuracy Positioning System. The tape is applied to signal the Mobile Robot where to stop.	-
⑮	Call/Door Box	13029-802	Used to issue a request for a Mobile Robot to go to the goal or to open a closed door. Installed at the goal or door to open.	-
⑯	Breakout Cable	14165-000	A D-SUB44 pin cable for digital I/O interface of the Mobile Robot.	-

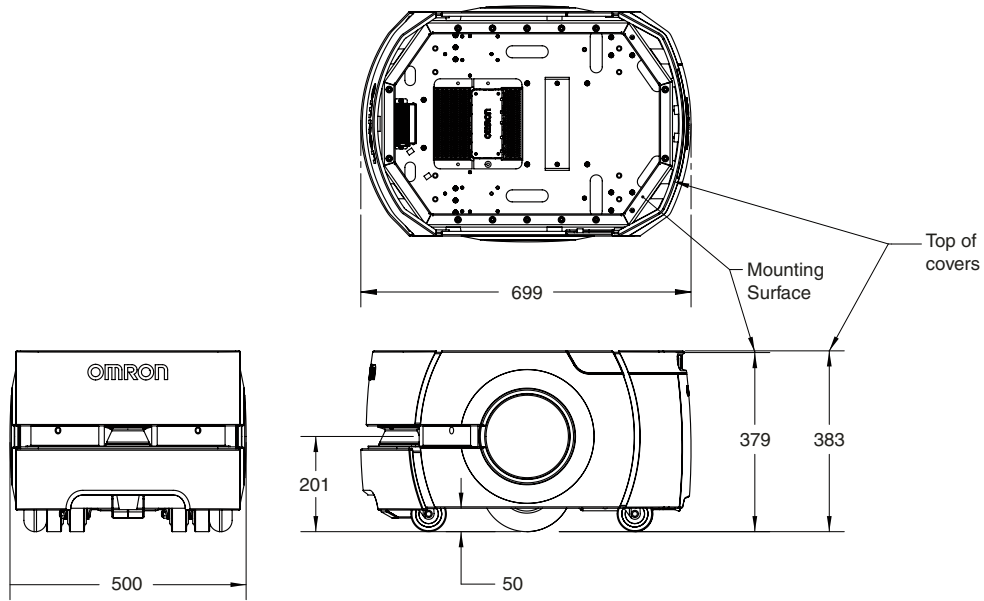
Dimensions

CAD data can be downloaded from Omron Adept Technologies Inc. website.
<http://www.adept.com/Robots-CAD-File>

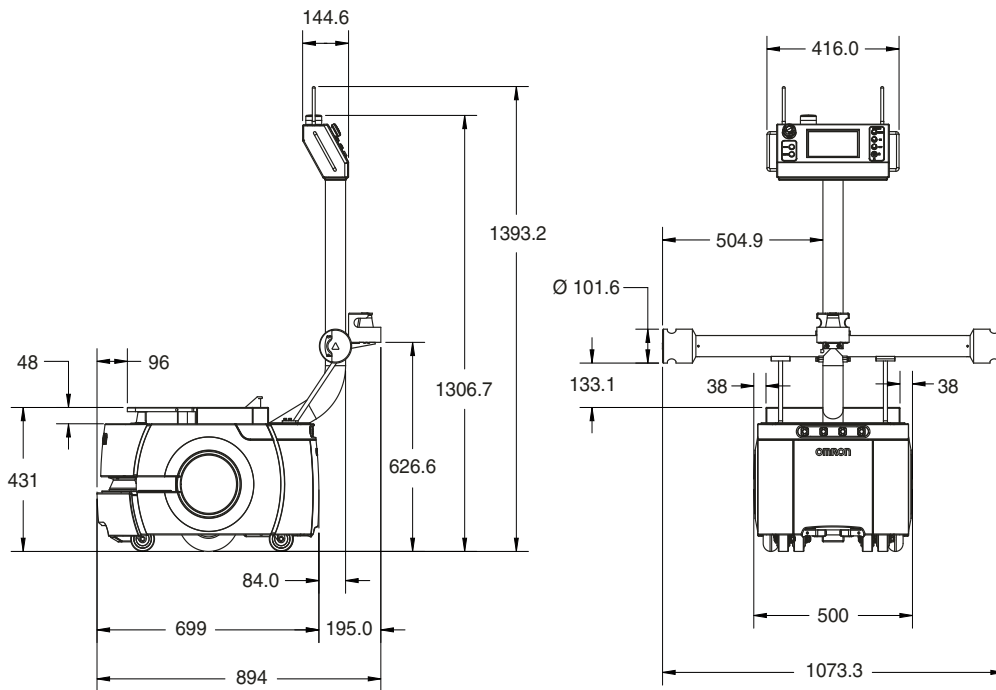
(Unit: mm)

Mobile Robots-LD Platform

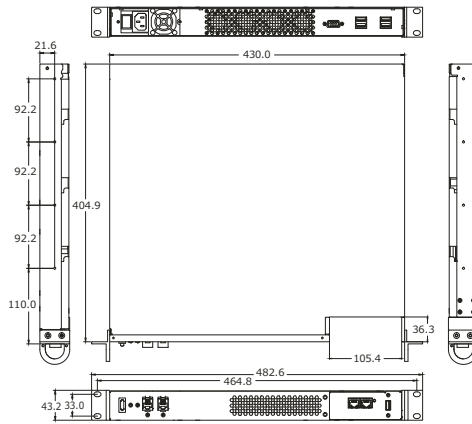
OEM



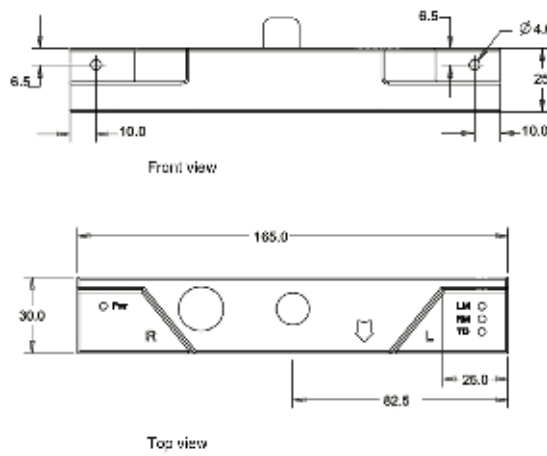
Cart Transporter



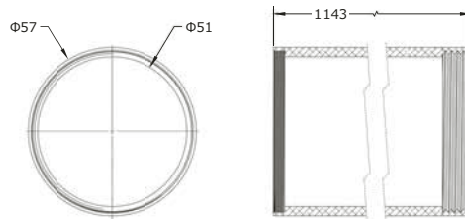
Enterprise Manager 1100



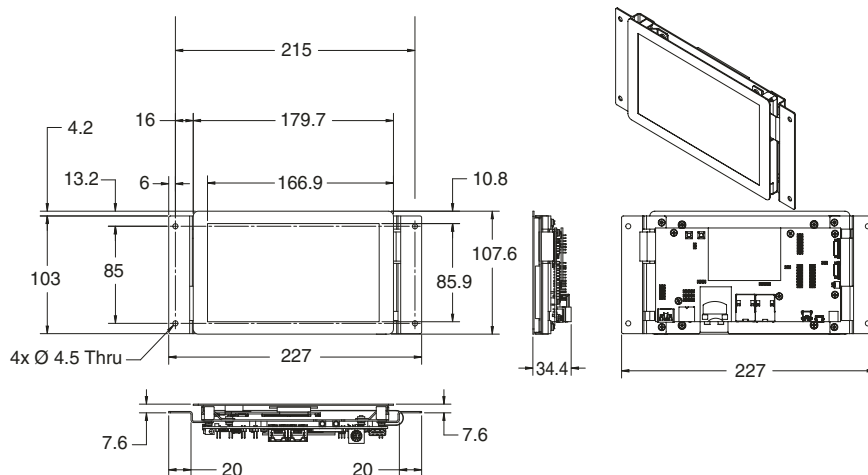
High Accuracy Positioning System



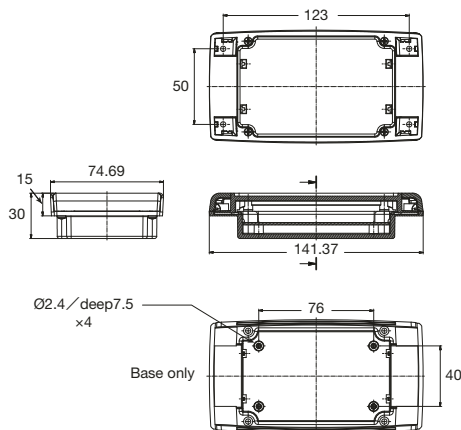
Acuity Localization



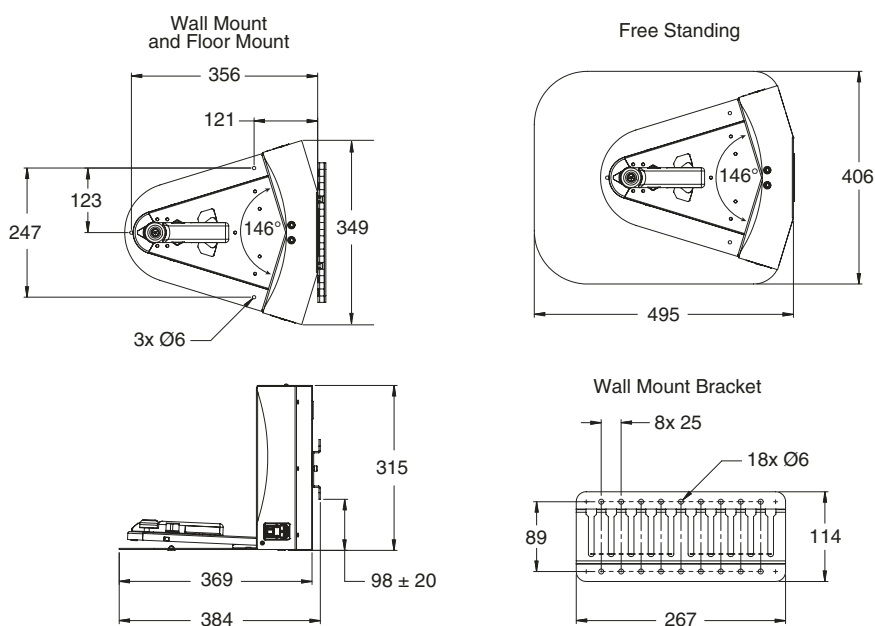
Touchscreen



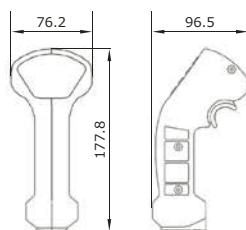
Call/Door Box

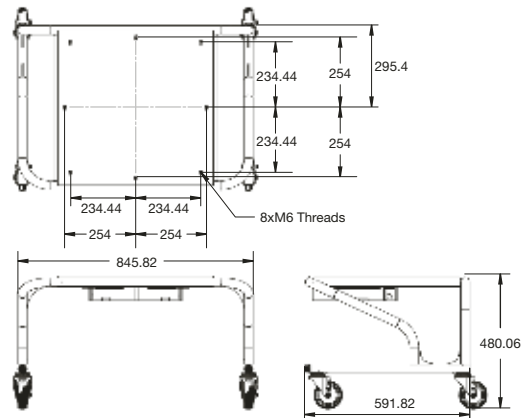


Docking Station



Joystick



Cart**Related Manuals**

Manual No.	English title
I611	Mobile Robots LD Platform User's Guide
I612	Mobile Robots LD Cart Transporter User's Guide
I613	Mobile Robots LD Platform Peripherals Guide
I614	Mobile Robots Software Suite User's Guide
I615	Enterprise Manager 1100 User's Guide
I616	Mobile Robot Safety Guide
I617	Advanced Robotics Command Language Reference Guide
I618	Advanced Robotics Command Language Enterprise Manager Integration Guide

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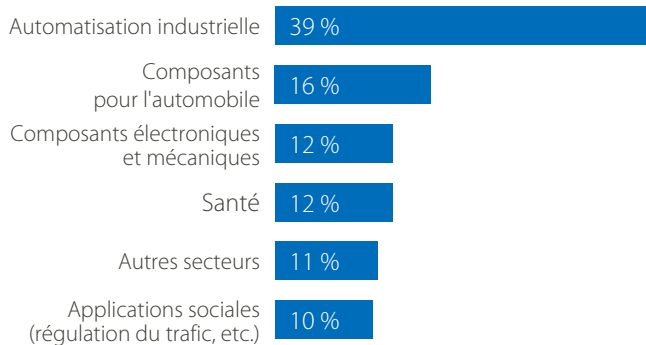
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